

Ch-1: Measurement and Experimentation

- (i) Physical Quantity = Numerical Value \times Unit
- (ii) L.C of V.C = Value of 1 M.S.D.
Total Nbs. of division on Vernier
- (iii) L.C of screw gauge = Pitch of screw gauge
Total division on circular scale
- (iv) Zero error \Rightarrow Correct Reading = Observed Reading - Zero error
- (v) $f = \frac{1}{T}$ or $T = \frac{1}{f}$
- (vi) $g = \frac{4\pi^2}{f}$
- (vii) slope of T^2 Vs l -graph
 $T = 2\pi \sqrt{\frac{l}{g}}$ or $T^2 = \frac{4\pi^2 l}{g}$
- (viii) $l = \frac{gT^2}{4\pi^2}$

Ch-2: Motion in One Dimension

- (i) Distance = Speed \times Time
- (ii) Displacement = Initial position - Final position
- (iii) Instantaneous speed = distance travelled in a short time interval / Time interval
- (iv) Speed = $\frac{\text{Distance}}{\text{Time}}$
- (v) Average speed = Total distance / Total time taken
- (vi) Velocity = Displacement / Time.
- (vii) Instantaneous velocity = Displacement / Total time taken

(viii) Acceleration (a) = Final velocity (v) - Initial velocity (u)
Time (t)

(ix) Equations of Motion: $\rightarrow V = u + at$
 $\rightarrow S = ut + \frac{1}{2}at^2$
 $\rightarrow V^2 - u^2 = 2as$ or $V^2 = u^2 + 2as$

Ch-3: Laws of Motion

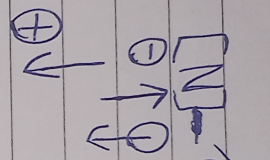
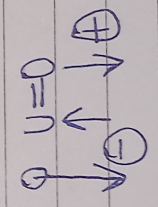
- (i) Force = $m \times a$ [m = mass, a = acceleration]
- (ii) Linear Momentum (P) = $m \times v$ [v = velocity]
- (iii) Change in momentum $\Rightarrow \Delta P = m \Delta v$
- (iv) Rate of change of momentum $\Rightarrow m \frac{(v-u)}{t} = ma$ or $F = ma$

(v) Universal Law of Gravitation
 $\Rightarrow F = G \frac{Mm}{r^2}$ [G = $6.67 \times 10^{-11} \text{ N m}^2 / \text{kg}^2$]

(vi) Acceleration due to gravity $\Rightarrow g = \frac{GM}{R^2}$ [g = 9.8 m/s^2]

(vii) Free fall

- $V = gt$
 - $S = \frac{1}{2}gt^2$
 - $V^2 = 2gS$
 - $V = u - gt$
 - $S = ut - \frac{1}{2}gt^2$
 - $V^2 = u^2 - 2gS$
- Mass and weight $\Rightarrow W = mg$ [N]



Ch-4: Pressure in Fluids and Atmospheric Pressure

- (i) Thrust = Force
- (ii) With Pressure \Rightarrow Thrust = Pressure \times Area
 Pressure = Thrust / Force
- (iii) Pressure $P = \frac{\text{Area}}{\text{depth}(h)} \times \text{density of liquid}(\rho) \times \text{acceleration}$
 due to gravity (g)
- (iv) Pressure exerted on side of the fluid
 $\Rightarrow P = \rho g h \Rightarrow P = \rho_0 + \rho g h$ $\rho_0 =$ Atmospheric Pressure
- (v) Pascal's Law $\Rightarrow \frac{F_1}{A_1} = \frac{F_2}{A_2}$ or $F_2 = A_2 \cdot \frac{F_1}{A_1}$

Ch-5: Upthrust in Fluids, Archimedes' Principle and Floatation

- (i) Upthrust = Weight of the liquid displaced by the submerged part of the body
- (ii) Density = $\frac{\text{Mass}}{\text{Volume}}$
 $[1 \text{ kg m}^{-3} = 10^{-3} \text{ g cm}^{-3} \text{ or } 10^3 \text{ m}^{-3} = 1000 \text{ kg m}^{-3}]$
- (iii) $R.D \Rightarrow \frac{\rho_s}{\rho_w} = \frac{m_s}{m_w}$ $[W = \text{Weight in } w]$
- (iv) $R.D = \frac{W_{\text{air}} - W_{\text{water}}}{W_{\text{air}} - W_{\text{liquid}}}$
- (vii) $W = \text{Volume of body} \times \text{Density of body} \times \rho_{\text{liquid}} \times g$
- (viii) $F_B = \text{Volume of submerged part of body} \times \rho_{\text{liquid}} \times g$

- (ix) $P_s = 1000 \cdot R D$
- (x) Buoyancy \rightarrow Body will float
 - $F_b > W \rightarrow$ Body will float
 - $F_b = W \rightarrow$ Body will sink
 - $F_b < W \rightarrow$ Body will sink
 - $a = \frac{W - F_b}{M}$
- (xi) • $M a = W - F_b$
Upthrust (Force) = $\frac{P_2 - P_1}{A}$ [$P_2 =$ Lower face; $P_1 =$ Upper face.]

Ch-6: Heat and Energy

- (i) $T_k = t(C + 273)$ [C to K]
- (ii) $T_F = \frac{9}{5} X t(C) + 32$ [C to F]
- (iii) $T_C = \frac{5}{9} X (F - 32)$ [F to C]
- (iv) $T_C = K - 273$ [K to C]

Ch-7: Reflection of Light

- (i) Image formed in two-inclined mirrors
 - $n = 360$ [odd] $\rightarrow n-1$] symmetrical placement
 θ [even] $\rightarrow n-1$
 - $n = 360$ [odd] $\rightarrow n$] Asy. symmetrical placement
 θ
- (ii) $R = 2f$
- (iii) On Next Page.

(iii) Spherical mirror formula:
 $\frac{1}{u} + \frac{1}{v} = \frac{1}{f}$ [f = Focal length of mirror, u = image distance from pole, v = object distance from pole]

(a) Sign Convention rules:
 (i) Concave Mirror
 * u is always -ve ($u < 0$), f is -ve ($f < 0$), for real image ($v < 0$) and for virtual image ($v > 0$).
 (ii) Convex Mirror
 u is always -ve ($u < 0$), f is +ve ($f > 0$), v is always +ve ($v > 0$).
 [Image is always formed behind the mirror]

(b) Magnification Relation
 Formula: $m = \frac{h_i}{h_o} = -\frac{v}{u}$

(ii) Nature of image from sign of m .
 (a) If m is -ve \rightarrow Image is real and inverted.
 (b) If m is +ve \rightarrow Image is virtual and erect.
 (c) Important points

(i) Concave Mirror
 (a) Real Image: (1) $u < 0$
 (2) $v < 0$
 (3) $m < 0$

(b) Virtual Image: (1) $u < 0$
 (2) $v > 0$
 (3) $m > 0$

(c) For distant object: (1) Image form near focus.
 For (2) m is small and negative.

- (ii) Convex Mirror
- (a) $u < 0$. (b) $v > 0$.
 - (c) $m > 0$. (d) Image is always virtual and erect.
 - (e) $|m|$ is always less than 1 ($|m| < 1$).
 - (f) Image is always diminished.
 - (d) size relation using m
 $|m| > 1 \rightarrow$ magnified image.
 $|m| = 1 \rightarrow$ same size
 $|m| < 1 \rightarrow$ diminished image.

Ch-8: Propagation of sound waves

- (i) $f = \frac{1}{T}$ or $T = \frac{1}{f}$
- (ii) $v = f \lambda$ ($v =$ speed of sound, $f =$ frequency, $\lambda =$ wave length)
- (iii) $d = v \times t$ (for echo condition)
- (iv) Higher frequency \rightarrow shriller sound.
Lower frequency \rightarrow deeper sound.
- (v) Speed of sound $(v) \propto \sqrt{f} = \frac{1}{T}$

Ch-9: Current Electricity

- (i) $\text{Current } (I) = \frac{\text{Charge } (Q)}{\text{time } (t)}$
- (ii) $\text{Charge} = \text{Current} \times \text{time}$
- (iii) $\text{Voltage } (V) = \frac{\text{Work } (W)}{\text{Charge } (Q)}$

(iv) Resistance $(R) = \frac{\text{Potential Difference (V)}}{\text{Current (I)}}$

(v) $V = IR$

(vi) $V = \frac{W}{q}$ [W] = Amount of work]

(vii) Factors on (R) Depends :-

(i) $R \propto l$

(ii) $R \propto \frac{1}{A}$

(iii) $V \propto I$

(iv) $I \propto V$